





# Thermomechanical Measurements for Energy Systems (MENR)

# Measurements for Mechanical Systems and Production (MMER)

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We will now analyze more in depth each one of the *functional blocks* of the general *measurement chain* ...



In the industry and in most modern measurement applications, the *measurement chain is electric* and the *information* passes through the different stages as **voltage signal** or as a **current !** 

Despite the enormous technological advancements of the last 30 years, the main <u>electrical visualizer instruments</u> can still be included in only **three** classes:

- 1. The *galvanometer*
- 2. The *oscilloscope*
- 3. The *digital voltmeter*

### The <u>analog</u> OSCILLOSCOPE →





Analog oscilloscope is the older type and can <u>instantaneously</u> display on the screen the waveform of the input signal !

The *periodic input signal* is combined on the fluorescent screen with an *internal sawtooth (sweep) signal* !

A trigger synchronizes the two signals !





Acceleration and collimation of the electron beam !





Sawtooth (sweep) and sinusoidal signal combination on the CRT screen !



spazio

### **Digital OSCILLOSCOPE ...**





The digital oscilloscope does the same tasks as the *analog* scope (and much more) but it is actually a *digital voltmeter* that samples the input signal and displays it on a VGA screen !

We will now study the most important *signal manipulation circuits* used in measurement instruments :



In modern and complex industry measurement system, the signal outputted by the transducer is almost always an *electrical signal* **v** or **i** for which, most of the time, we need to <u>enhance the information content</u> (the **intensity of the measurand**) !

It is always possible to measure a <u>voltage with an</u> <u>amperometer</u> and a <u>current with a voltmeter</u> ...





### The rectifier diode :





a) The **SCR diode** works here as a <u>half-wave rectifier</u> !





b) The *Gretz bridge* with 4 SCR diodes works here as a *full- wave rectifier* !

### The low-pass "RC" circuit



Let's study the *two electric circuits* 

input (voltage) signal:  $v_i = (R + X_C) \cdot i$ output (voltage) signal:  $v_o = X_C \cdot i$ 

the current is  $i = \frac{v_i}{R + X_C}$  and the output voltage:  $v_o = X_C \cdot \frac{v_i}{R + X_C} = \frac{v_i}{\frac{R}{X_C} + 1}$ but  $X_C = \frac{1}{j\omega C}$  is the *capacitive reactance*, therefore the output/input ratio is :  $\frac{v_o}{v_i} = \frac{1}{j\omega RC + 1}$ Considering  $\omega_c = \frac{1}{RC} = \frac{1}{\lambda}$  the output/input ratio is also:  $\frac{v_o}{v_i} = \frac{1}{j\omega\lambda + 1}$  We can calculate the modulus of the previous complex function :

And the phase delay:  $\varphi = arctg(-\omega\lambda)$ 

 $G = \frac{v_o}{v_i} = \frac{1}{\sqrt{\left(\frac{\omega}{\omega_c}\right)^2 + 1}}$ 

the *gain* !

We recognize the *frequency response* of a simple 1<sup>st</sup> order electric signal manipulation stage !



for 
$$\omega = 0$$
  $G = 1$   
 $\omega \rightarrow \infty$   $G = 0$   
 $\omega = \omega_c$   $G = \frac{1}{\sqrt{2}}$ 

The RC circuit is a *low-pass filter* (*one pole Butterworth* 

**filter**) with a -3 db cut-off frequency: 
$$f_c = \frac{1}{2\pi RC}$$
  
Note that for  $|j\omega CR| >> 1$  which is  $\omega >> \frac{1}{CR} = \omega_c$ 

the *output signal* is also the "integral" of the input signal:

$$v_o(t) = \frac{1}{\lambda} \cdot \frac{1}{j\omega} v_i(t)$$

### The high-pass "CR" circuit



The *two electric circuits* equations now are:

input (voltage) signal:  $v_i = (X_C + R) \cdot i$ 

output (voltage) signal:

$$v_{o} = R \cdot i$$

which now result in :  $v_o = R \cdot \frac{v_i}{X_c + R}$  with the same notations:  $X_c = \frac{1}{i\omega C}$   $\omega_c = \frac{1}{RC} = \frac{1}{\lambda}$ The output/input ratio is :  $\frac{v_o}{v_i} = \frac{R}{X_c + R} = \frac{j\omega CR}{1 + j\omega CR} = \frac{j\omega\lambda}{1 + j\omega\lambda}$ 

It is also a **1**<sup>st</sup> order electric signal manipulation stage with a <u>gain</u> of :





For 
$$|j\omega CR| \ll 1$$
 or  $\omega \ll \frac{1}{CR} = \omega_c$   
we get  $G = \frac{v_o}{v_i} \cong j\omega CR \ll 1$   
or  $v_o(t) = \lambda \cdot j\omega \cdot v_i(t)$  the output signal is  
the "derivative" of the input signal !

if we consider, for example, a sinusoidal signal

 $v_i(t) = Vsen\omega t = Ve^{j\omega t}$  and we *derivate* and *integrate* it :

 $(j\omega) \rightarrow$  is a <u>derivative operator</u>

 $\left(\frac{1}{j\omega}\right)$ 

 $\rightarrow$  is an <u>integration operator</u>

$$\frac{dv_i(t)}{dt} = \frac{dVe^{j\omega t}}{dt} j\omega \cdot Ve^{j\omega t} = (j\omega) \cdot v_i(t)$$

$$\int v_i(t)dt = \int V e^{j\omega t} dt = \frac{V}{j\omega} \cdot e^{j\omega t} = \left(\frac{1}{j\omega}\right) \cdot v_i(t)$$

## The operational amplifier OA :



We will <u>not</u> study the inner electronic circuits of the OA but the important <u>operational features</u> it offer for the measurements !



Ideal OA characteristics :

Amplification Input impedance Otput impedance Band width Offset voltage  $\begin{array}{l} \mathsf{A} \rightarrow \infty \quad (10^7) \\ \mathsf{Z}_{\mathsf{i}} \rightarrow \infty \quad (10^{10} \,\Omega) \\ \mathsf{Z}_{\mathsf{o}} \rightarrow 0 \quad (100 \,\Omega) \\ \mathsf{BW} \rightarrow \infty \\ \mathsf{V}_{\mathsf{io}} \rightarrow 0 \end{array}$ 



The open loop OA can amplify a voltage signal  $V_o = A \cdot (V_+ - V_-)$  but NOT over its supply voltages !

If we have  $V_{cc} = \pm 10V$  and  $A = 10^7$ Then  $\pm 10V = 10^7 \cdot (V_+ - V_-)_{MAX}$ 

and  $(V_{+} - V_{-})_{MAX} = \frac{20V}{10^7} = 2\,\mu V$  is the

maximum input signal the OA can handle!

The OA goes into *saturation* for:

 $|V_i| = |V_+ - V_-| > 2\mu V$ 

The real *open-loop frequency response* curve is determined by the *Gain Bandwidth Product (GBP)* ...

$$20 \log(A)$$
 or  $20 \log \frac{V_{out}}{V_{in}}$  in dB





At the virtual earth summing junction we have:

input signal:  $V_i = R_i \cdot i_i$ output signal:  $V_o = R_f \cdot i_f$ 

The current at the virtual earth point is:  $i_i + i_f = 0$ And because  $i_f = -i_i$  we have

 $V_{-} \cong V_{+} = 0$ 

$$V_o = -R_f i_i = -R_f \frac{V_i}{R_i}$$

which is the *static characteristic curve* of the device and gives also the *GAIN* of the amplifier:

The Operational Amplifier <u>CAN NOT</u> be used as an amplifier in the *open loop configuration* !

Therefore, we must *connect two resistors* at the terminals as showed in the figure, realizing the *inverting operational Amplifier* configuration:



To get a "positive" signal amplification we have to switch to the *non-inverting operational amplifier* configuration:



Because of the "high input impedance" of the OA device, there is *virtually no current* entering the + terminal of the OA and we have now:  $V_{-} \cong V_{+} = V_{i}$  and  $i_{f} = i$ 

So, the output signal can be written as  $V_o = V_f + V_i$ where  $V_f = R_f \cdot i_f$  and  $V_i \cong V_- = R_i \cdot i$ 

In the end we have: 
$$V_o = R_f i_f + V_i = R_f i + V_i = R_f \frac{V_i}{R_i} + V_i$$

# And the *static characteristic curve* now is:



with a *positive GAIN* !



Both configurations have *much lower amplification* than  $10^6 - 10^7$  however the amplification "can be designed" by choosing the two resistance values ! Even if the <u>non-inverting configuration</u> may seem preferable, the <u>inverting configuration</u> has important applications ...

### The voltage summing OA :



Here we wish to sum two voltages  $V_a$  and  $V_b$ 

From the inverting OA characteristic curve, we have:  $V_o = -\frac{R_f}{R_i}V_i = -R_f i_i$ 

vith 
$$i_i = \frac{V_i}{R_i} = i_a + i_b = \frac{V_a}{R_a} + \frac{V_b}{R_b}$$

If we design the circuit inputs with the two resistance values being equal:  $R_a = R_b = R$ 

We can simplify the above equation and we obtain : *input voltages* !

$$V_o = -\frac{R_f}{R} \left( V_a + V_b \right)$$

V

which is the *sum of the two* 

Note that summing two voltages means physically to sum the two input currents !

### The <u>active low-pass filter (integrator)</u> :



The gain of the inverting OA is: 
$$v_o = -\frac{Z_f}{Z_i}v_i$$
  
with  $Z_i = R_i$  and  $Z_f = X_{Cf} = \frac{1}{j\omega C_f}$   
Therefore  $v_o = -\frac{1/j\omega C_f}{R_i} \cdot v_i = -\frac{1}{j\omega} \cdot \frac{1}{C_f R_i}v_i = -\frac{1}{j\omega} \cdot \omega_c \cdot v_i$ 

the *output signal* is the <u>electric integral</u> of the input signal !

If we wish to amplify the output, then we have to put an extra resistance  $R_f$  on the feedback arm and the extra gain will be :  $G = R_f / R_i$ 

### The <u>active high-pass filter (derivative)</u> :



The gain is still: 
$$v_o = -\frac{Z_f}{Z_i}v_i$$
  
with  $Z_i = X_{Ci} = \frac{1}{j\omega C_i}$  and  $Z_f = R_f$   
so  $v_o = -\frac{R_f}{1/j\omega C_i}v_i = -j\omega \cdot C_i R_f \cdot v_i = -j\omega \cdot \frac{1}{\omega_c} \cdot v_i$  the electric  
*derivative*



Consider now that the OA accepts TWO voltages at the input terminals  $V_{+} = V_{2}$  and  $V_{-} = V_{1}$  both referred to earth, and amplifies its difference:  $V_{o} = A(V_{2} - V_{1})$  ... But this is true in the IDEAL case ! In the reality, there are <u>TWO slightly different amplifications</u> at the inputs:  $V_{o} = A_{2}V_{2} - A_{1}V_{1}$  ...

This situation can be effectively described by the *differential input*:  $V_d = V_2 - V_1$  and the *common mode input*:  $V_c = \frac{V_1 + V_2}{2}$  which is the <u>mean distance from the earth reference</u> of the two input voltages.

For an ideal OA we would have  $A_1 = A_2 = A$  and the OA would amplify only the differential input, completely eliminating the common mode input !

This situation can be effectively described by the *differential amplification*:  $A_d = \frac{A_1 + A_2}{2}$  which operates on  $V_d$  and by the *common mode amplification*:  $A_c = A_2 - A_1$  which operates on  $V_c$ <sup>2</sup> To minimize this problem the OA must be designed with a high  $A_d$  and a very small  $A_c$  which means  $A_1 \approx A_2$ 

The ratio between the two amplifications is an important <u>quality parameter</u> of the OA, the <u>Common Mode</u> <u>Rejection Ratio</u>:  $CMRR = \frac{A_d}{A_c}$  often expressed in logarithmic scale

Values range from 60 dB up to 120 Db for high quality OA ...

$$CMRR = 20\log\frac{A_d}{A_c}$$

### The Instrumentation Amplifier IA :



The most employed amplifier in measurements is designed with two stages:

- 1. A very high input impedance stage ( $10^{10} \Omega$ )
- 2. A differential amplification stage

It has generally a very high **Common Mode Rejection Ratio** (> 100 dB) which makes it suitable to amplify *floating signals*  $(v_2 - v_1) \dots$ 

The (differential) **GAIN** is :

$$G = \frac{v_o}{v_i} = \frac{R_4}{R_3} \left( 1 + \frac{2R_2}{R_1} \right)$$

## The Carrier AC Amplifier :



The *Carrier Amplifier* is an <u>AC amplifier</u> which does NOT amplify <u>DC signals</u> or <u>components</u> !

It is designed on the "signal modulation and demodulation" principle of radio transmission !

The low frequency  $(f_s)$  signal is modulated by the carrier frequency  $(f_c)$  which is the only frequency the amplifier is able to amplify !

A *phase sensitive demodulator* and a *low pass-filter* return an amplified low frequency signal !



Demodulation





Carrier

Demodulater Signal.

### The <u>Wheatstone Bridge</u> :



Two resistances r and r' are connected in parallel and a *galvanometer* G is connected in a bridge configuration across the two resistances in the points A and B ...

We move now the point A and B on the resistances so to have <u>zero current</u> though the galvanometer, which means also:  $V_A = V_B$ 

In this situation we identified 4 resistances :  $R_1$ ,  $R_2$ ,  $R_3$ ,  $R_4$  for which we can write the following equations:

$$V_{CA} = V_{CB} \longrightarrow R_1 I_1 = R_4 I_2$$
$$V_{AD} = V_{BD} \longrightarrow R_2 I_1 = R_3 I_2$$

Making the ratio of the two equations, we get:  $\frac{R_1}{R_2} = \frac{R_4}{R_2}$  or  $R_1R_3 = R_2R_4$ 

the *bridge equilibrium equation* !

No current through the bridge means also  $V_A - V_B = 0$  therefore, in practical application, we can substitute the *galvanometer* with a *millivoltmeter* !



The *Wheatstone Bridge* is a "zero method" electric network used for resistance measurements:

If  $R_x = R_1$  is unknown, we equilibrate the bridge by operating on R2 and, knowing the values of  $R_2$ ,  $R_3$ ,  $R_4$ , we get:

$$R_x = R_1 = \frac{R_2 R_4}{R_3}$$

However, this is NOT the main use of the Wheatstone Bridge ...

We might have a resistance  $R_1$  that changes slightly its value  $\Delta R_1$  for physical reasons ...

It is possible to read this small change directly on the voltmeter indicator but, to do so, we need to know the **bridge graduation curve** (or <u>static characteristic equation</u>):  $V_{AB} = f(\Delta R_1)$ 

If we consider for simplicity a bridge with 4 equal resistances:  $R_1 = R_2 = R_3 = R_4 = R$  and a variation  $\Delta R_1$  only on the resistance  $R_1$ , we get:

The complete *Wheatstone Bridge characteristic curve* :

 $\Delta R_1$  $\Delta e$ ER

which is clearly NON linear !



However, if the variation  $\Delta R_1 << R$  is

really <u>very small</u>:  $\frac{\Delta R_1}{R} < 0.01$ 

Then, the denominator of the graduation curve can be approximated with "1"

$$\frac{1}{2}\frac{\Delta R_1}{R} << 1$$

and the characteristic equation has been linearized !

<u>Linearized</u> Wheatstone Bridge characteristic curve !

Same result if the only resistance with a small variation  $\Delta R_2$  would have been  $R_2$  on the second arm of the bridge:



negative because R2 is in the negative term of the equilibrium equation:  $R_1R_3 - R_2R_4 = 0$ 

In the case of simultaeous small variations of all 4 resistances of the Wheatstone Bridge, we would get:

$\Delta e$	_ 1	$\left(\Delta R_{1}\right)$	$\Delta R_2$	$\Delta R_3$	$\Delta R_4$
E	$^{-}4$	$\overline{R}$	R	$\overline{R}$	$\overline{R}$

The *Full Wheatstone Bridge characteristic curve* ! (note the sign alternations ... very important property ...)